GEM FOUNDATION calculate share explore PENQUAK **10TH ANNIVERSARY** 2020

A DECADE OF SERVING OQ ENGINE TO ANALYZE SEISMIC HAZARD & RISK TO REDUCE LOSS OF LIVES AND PROPERTIES FOR A SAFER AND RESILIENT FUTURE.

For a world that is resilient to earthquakes | global quakemodel, org

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OQ - beyond tailor to fit

Working with the OQ Engine for site-specific, national and regional hazard assessment

Laurentiu Danciu, ETH Zurich | Swiss Seismologic Service Switzerland |





to begin with

- ETH Zurich Swiss Seismological Service
- GEM1 hazard team
- In House Expertise
- GSHAP legacy (Giardini et al 1999)
- First Regional Projects: SHARE (Europe) and EMME (Middle East)
- First National Model: Seismic Hazard Model
- PEGASUS/PRP Project (P. L. A. Renault et al 2014)





First steps: Regional Hazard Models

The 2013 European Seismic Hazard Model (Woessner et al 2015) 1st Regional Hazard Model Computed with OpenQuake (v.07beta)



peak ground acceleration (g)

The ESC-SESAME unified hazard model for the European-Mediterranean region Jimenez et al (1999) Unity Model: Unified seismogenic source model One Attenuation model: Ambraseys 1996, Musson 1999, Papaioanou and Papazachos 1999



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First steps: Regional Hazard Models

The 2013 European Seismic Hazard Model (Woessner et al 2015) 1st Regional Hazard Model Computed with OpenQuake (v.07beta)

- Iterative development process
 - -Tailor the models
 - -Add features to OpenQuake







Iterative development process - Handling Requirements

Key features: Library of the Ground Motion Models

- First set of GMPEs implemented in OQ hazard library (ESHM13, NGA WEST, European & Global GMPEs)
- Establish the testing framework for GMPEs implementation
- GEM Science Tools (GSIM toolkit, Weatherill et al 2015)

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GEM (**O**))

Key features: Library of the Ground Motion Models

The 2020 European Seismic Hazard Map: Regional Backbone Model (Weatherill et al 2020) - OQ Hazard libraries - GSIM Trellis Plots

OPENQUAKE

Multiple GMPEs

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Regional Backbone Models.

Trellis Plots

Key features: Library of the Ground Motion Models

The 2015 Swiss Hazard Model (Wiemer et al 2015)

- OQ Hazard libraries Complex Ground Motion model, stochastic and adjusted empirical ground motion models
- Vs30-kappa and small magnitude adjustments
- Single station sigma
- Extending Ground Motion Models (2014)

COC COC C

- OpenQuake offers two methods for processing the logic tree:
 - Monte Carlo Sampling: useful in case of large logic trees (e.g. LT containing uncorrelated uncertainties on seismic sources)
 - Path Enumeration: useful in case of small logic trees (e.g. LT including few GMPEs, correlated uncertainties)

Computational time: 65h - 100k Sampling | full output , no post processing | 48CPUs - 256Gb RAM

2015 Swiss Hazard Model (Wiemer et al 2015)

- 5 seismogenic source model | 36 GMPEs | ~ 1M End-Branches | 100K sampled

COC Key features: Modelling Uncertainties

• OpenQuake offers two methods for processing the logic tree:

- Monte Carlo Sampling: useful in case of large logic trees (e.g. LT containing uncorrelated uncertainties on seismic sources)
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Douglas et al 2015

No more need to define inputs for each logic tree path and run calculation in a batch and to post-process the results of different realisations

the OpenQuake 10 year anniversary | webinar 22nd of October 2020

Unc

Key features: Continuous Update and Integration

Tips for running large hazard calculations

Running large hazard calculations, especially ones with large logic trees, is an art, and there are various techniques that can be used to reduce an impossible calculation to a feasible one.

The first thing to do

The first thing to do when you have a large calculation is to reduce it so that it can run in a reasonable amount of time. The simplest way to do that is to reduce the number of sites, for instance by considering a small geographics portion of the region interested, of by increasing the grid spacing. Once the calculation has been reduced, you can run it and determine what are the factors dominating the run time.

As we discussed in section <u>common mistakes</u>, you may want to tweak the quadratic parameters (maximum_distance, area_source_discretization, rupture_mesh_spacing, complex_fault_mesh_spacing). Also, you may want to choose different GMPEs, since some are faster than others. You may want to play with the logic tree, to reduce the number of realizations: this is especially important, in particular for event based calculation were the number of generated ground motion fields is linear with the number of realizations.

Once you have tuned the reduced computation, you can have an idea of the time required for the full calculation. It will be less than linear with the number of sites, so if you reduced your sites by a factor by a number of 100, the full computation will take a lot less than 100 times the time of the reduced calculation (fortunately). Still, the full calculation can be impossible because of the memory/data transfer requirements, especially in the case of event based calculations. Sometimes it is necessary to reduce your expectations. The example below will discuss a concrete case.

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Michele Simionato OQ Lead Architect https://docs.openquake.org/oq-engine/advanced/index.html

Take Away Message

- OpenQuake A Game Changer
- Continuous improvement, facilitates evolution of models and tools
- Outstanding support for developing and implementing - hazard & risk models & tools
- GEM excellent community engagement and support

The OpenQuake Engine is an open source application that allows users to compute seismic hazard and seismic risk of earthquakes on a global scale. It runs on Linux, macOS and Windows, on laptops, workstations, standalone servers and multi-node clusters. DOI: 10.13117/openquake.engine

Current stable

Current stable version is the OpenQuake Engine 3.10 'Ulomov'. The documentation is available at https://github.com/gem/oq-engine/tree/engine-3.10#Openquake-engine. . What's new Documentation (master tree) General overview . About . FAQ . About . FAQ . Anout . FAQ . Anout . Commands . Architecture . At the commentation (master tree) . About . About . About . About . About . Active commands . Architecture . At the commentation (master tree) . About . Abo

To many researchers and scientists contributing to the development of the regional and national models

THANK YOU!

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